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# Inverse Problem of Determining the Coefficient and Kernel in an Integro - Differential Equation of Parabolic Type

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**Abstract.** This article is concerned with the study of the unique solvability of inverse boundary value problem for integro-differential heat equation. To study the solvability of the inverse problem, we first reduce the considered problem to an auxiliary system with trivial data and prove its equivalence (in a certain sense) to the original problem. Then using the Banach fixed point principle, the existence and uniqueness of a solution to this system is shown.

## INTRODUCTION AND FORMULATION OF PROBLEM

Mathematical physics usually studies well-posed problems, that is, the problems that have solutions which are unique and stable to small changes in the data in suitable functional spaces. Such problems, as a rule, are called direct problems. In this case, it is assumed that a differential equation is specified, as well as certain initial and boundary conditions. However, in applications there are interesting problems, where the differential (or integro-differential) equation is only partially specified, namely, some functions that are part of the differential equation (either in the right-hand side, integrand in integro-differential equations or the initial and boundary conditions) remain unknown. The problems, in which these unknowns are to be determined on some information about the solutions of direct problems for differential equations, are called inverse problems.

Inverse problems are widely used to solve practical problems in many branches of science and engineering. The study of inverse kernel determination problems for hyperbolic and parabolic integro-differential equations with an integral term of convolution type is very interesting from both the practical and theoretical viewpoint. Such equations in the case of a parabolic equation arise in problems of heat propagation in media whose state at a given time instant depends on their state at all previous time instants.

The inverse problem finding coefficient for parabolic and hyperbolic equations is studied in the works of many authors; a detailed bibliography can be found in [1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11]. In last articles are proved that the problem is locally solvable in time or in the case where the norms of its data are sufficiently small.

In [12, 13, 14, 15, 16, 17, 18] papers are considered inverse problem for a fractional diffusion equation determining the reaction coefficient depending of the spatial variable and on time. Local existence and global uniqueness, a stability theorems are proved.

Inverse problems for integro-differential equation of multi and one-dimensional parabolic type are investigated by many author with initial, initial-boundary, overdetermination conditions (see [19, 20, 21, 22, 23, 24, 25, 26, 27]). As a result, is proved the global unique solvability of the inverse problem and obtained a stability estimate of a solution of the inverse problem.

Inverse problems for integro-differential equation of parabolic type can be found in papers [28, 29, 30, 31, 32, 33, 34, 35, 36, 37, 38, 39, 40, 41] and the problems studied in them are close to the problem considered in this article. In the above papers, the existence and uniqueness theorems were proved for the solution of the problem of finding the kernel for various overdetermination conditions.

In the present paper, we investigate the inverse problem of the simultaneous determination of two unknowns: the coefficient  $a(t)$  and the heat relaxation function  $k(t)$  in the integro-differential heat equation. For this, two simple observations are given at two different points.

Consider the problem of determining of functions  $u(x,t)$ ,  $a(t)$ ,  $k(t)$ , from the following equations:

$$u_t - u_{xx} + a(t)u = \int_0^t k(t-\tau)u(x,\tau)d\tau, \quad (x,t) \in D_T, \quad (1)$$

$$u|_{t=0} = \varphi(x), \quad x \in [0, 1], \quad (2)$$

$$u|_{x=0} = u|_{x=1} = 0, \quad \varphi(0) = \varphi(1) = 0, \quad t \in [0, T], \quad (3)$$

$$u(x_0, t) = h_0(t), \quad \int_0^1 u(x, t)dx = h_1(t), \quad x_0 \in (0, 1), \quad \varphi(x_0) = h_0(0), \quad \int_0^1 \varphi(x)dx = h_1(0), \quad (4)$$

where  $D_T = \{(x,t)|x \in (0, 1), 0 < t \leq T\}$ ,  $T > 0$  is arbitrary fixed number.

In equation (1) on the left side there is a heat conduction operator acting on the function  $u(x,t)$ , and on the right side there is a convolution type integral. In fact, if  $a$  and the kernel  $k$  of the integral are known in equation (1), then the problem of finding the function  $u$  from equation (1), based on conditions (2), (3) is called the direct problem. Note that direct problem in this case is initial-boundary problem for the equation (1).

Since after finding functions  $a$  and  $k$  the solution of the direct problem becomes known, it is convenient to call the solution of the inverse problem (1)-(4) the problem of finding functions  $u$ ,  $k$ ,  $a$ .

In the inverse problem, it is required to find  $a$  and the kernel  $k$  of the integral in equation (1) if the additional conditions (4) are known with respect to the solution of the direct problem. The functions  $\varphi$  in condition (2) and the function  $h_i$  in (4) are called the data of the direct and inverse problems, respectively. The last conditions in (4) are matching conditions for given functions.

## INVESTIGATION OF DIRECT PROBLEM

Before we proceed to studying the inverse problem, let us show that the direct problem has a unique solution.

Let  $a(t)$ ,  $k(t) \in C[0, T]$ ,  $T > 0$  being some number. Then the direct problem (1)-(3) is equivalent to the problem of determining the function  $u(x,t)$  from the equation

$$U_t - U_{xx} = \int_0^t k_0(t,\tau)U(x,\tau)d\tau, \quad (5)$$

$$U|_{t=0} = \varphi(x), \quad (6)$$

$$U|_{x=0} = 0, U|_{x=1} = 0, \quad (7)$$

where  $U(x,t) = e^{-\int_0^t a(\tau)d\tau}u(x,t)$ ,  $k_0(t,\tau) = k(t-\tau)e^{-\int_\tau^t a(\alpha)d\alpha}$ .

**Lemma 1.** *If  $\varphi(x) \in C(0, 1)$ ,  $k(t) \in C([0, T])$ ,  $\varphi(0) = \varphi(1) = 0$  then there is the unique classical solution  $U(x,t)$  to the problem (5)-(7) of the class  $C^{2,1}(D_T)$ .*

$C^{2,1}(D_T)$  is the class of twice continuously differentiable with respect to  $x$  and once continuously differentiable with respect to  $t$  in the domain  $D_T$  of functions. In what follows we also use the usual class  $C(D_T)$  of continuous in  $D_T$  functions.

**Proof.** Problem (5)-(7) is equivalent to the integral equation

$$U(x,t) = \int_0^1 G(x,\xi,t-\tau)\varphi(\xi)d\xi + \int_0^t \int_0^1 G(x,\xi,t-\tau) \int_0^\tau k_0(t,\tau)U(\xi,\alpha)d\alpha d\xi d\tau, \quad (8)$$

where

$$G(x,\xi,t-\tau) = 2 \sum_{n=1}^{\infty} e^{-(\pi n)^2(t-\tau)} \sin(\pi n \xi) \sin(\pi n x)$$

is the Green function of the initial-boundary problem for one-dimensional heat equation.

Let us denote the sum of the first one summand on the right-hand side of (8) by  $\Phi(x,t)$ , for this equation, we consider in the domain  $D_T$  the sequence of functions

$$U_n(x,t) = \Phi(x,t) + \int_0^t \int_0^1 G(x,\xi,t-\tau) \int_0^\tau k_0(t,\tau)U_{n-1}(\xi,\alpha)d\alpha d\xi d\tau, \quad n = 1, 2, \dots, \quad (9)$$

where  $U_0(x,t) = 0$  for  $(x,t) \in D_T$ . If the conditions of Lemma 1 are fulfilled, we have that  $\Phi(x,t) \in C^{2,1}(D_T)$  [42]. Then, it follows from (8) that all  $U_n(x,t)$  in  $D_T$  possess the same property.

Denote  $Z_n(x,t) = U_n(x,t) - U_{n-1}(x,t)$  and  $\Phi_0 = \|\Phi\|_{C(D_T)}$ . According to the formula (8), we estimate  $Z_n(x,t)$  in the domain  $D_T$ :

$$\begin{aligned} |Z_1(x,t)| &\leq \Phi_0, \\ |Z_2(x,t)| &\leq \int_0^t d\tau \int_{\mathbb{R}^n} G(x-\xi, t-\tau) \int_0^\tau |k_0(\tau, \alpha)| |Z_1(\xi, \alpha)| d\alpha d\xi \leq \\ &\leq \Phi_0 k_0 k_{00} \frac{t^2}{2!}, \quad k_0 = \max_{t \in [0, T]} |k(t)|, \quad k_{00} = e^{a_0 T}, \quad a_0 = \max_{t \in [0, T]} |a(t)|, \\ |Z_3(x,t)| &\leq \int_0^t \int_0^l G(x, \xi, t-\tau) \\ &\times \int_0^\tau |k_0(\tau, \alpha)| |Z_2(\xi, \tau-\alpha)| d\alpha d\xi d\tau \leq \Phi_0 (k_0 k_{00})^2 \frac{t^4}{4!}. \end{aligned}$$

Thus, for arbitrary  $n = j$ , we have

$$|Z_j(x,t)| \leq \Phi_0 (k_0 k_{00})^{j-1} \frac{t^{2(j-1)}}{2(j-1)!}.$$

It follows from the above estimates that the series

$$\sum_{n=1}^{\infty} [U_n(x,t) - U_{n-1}(x,t)]$$

converges in  $D_T$ , and its sum  $U(x,t)$  belongs to the functional space  $C^{2,1}(D_T)$ . Since the sequence  $U_n(x,t)$ , determined by equality (9) converges to  $U(x,t)$  uniformly in  $D_T$ , then  $U(x,t)$  is a solution of equation (8).

Now show that this solution is the only one. Suppose that there are two solutions  $U^1(x,t)$  and  $U^2(x,t)$ . Then their difference  $Z(x,t) = U^2(x,t) - U^1(x,t)$  is a solution to the equation

$$Z(x,t) = \int_0^t \int_0^l G(x, \xi, t-\tau) \int_0^\tau k_0(\tau, \alpha) Z(\xi, \alpha) d\alpha d\xi d\tau.$$

Let  $\tilde{Z}(t)$  denote the supremum of the module of the function  $Z(x,t)$  for  $x \in (0, 1)$  at each fixed  $t \in (0, T)$ . Then we have the inequality

$$\tilde{Z}(t) \leq k_0 k_{00} T \int_0^t \tilde{Z}(\tau) d\tau, \quad t \in [0, T].$$

Applying the Gronwall lemma here, we obtain that  $\tilde{Z}(t) = 0$  for  $t \in [0, T]$ , which means that  $Z(x,t) = 0$  in  $D_T$ , i.e.  $U^1(x,t) = U^2(x,t)$  in  $D_T$ . Therefore, equation (8) has a unique solution in  $D_T$ . The lemma is proved.

## AUXILIARY PROBLEM

Suppose that the data of problem (1)-(4) are sufficiently smooth functions. The degree of smoothness for each function will be determined later.

The following assertion is true:

**Lemma 2.** *Problem (1)-(4) is equivalent to the following auxiliary problem of determining functions  $u(x,t)$ ,  $k(t)$ ,  $a(t)$ :*

$$\omega_t - \omega_{xx} + a'(t)\varphi''(x) + a'(t) \int_0^t \omega(x, \tau) d\tau + a(t)\omega(x,t) = k(t)\varphi''(x) + \int_0^t k(\tau)\omega(x, t-\tau) d\tau, \quad (x,t) \in D_T, \quad (10)$$

$$\omega|_{t=0} = \varphi^{(IV)}(x) - a(0)\varphi'(x), \quad x \in [0, 1], \quad (11)$$

$$\omega|_{x=0} = 0, \omega|_{x=1} = 0, \quad t \in [0, T], \quad (12)$$

$$\omega|_{x=x_0} = h_0''(t) + a'(t)h_0(t) + a(t)h_0'(t) - k(t)\varphi(x_0) - \int_0^t k(\tau)h_0'(t-\tau)d\tau, \quad t \in [0, T], \quad (13)$$

$$\int_0^1 \omega(x,t)dx = h_1''(t) + a'(t)h_1(t) + a(t)h_1'(t) - k(t)h_1(0) - \int_0^t k(\tau)h_1'(t-\tau)d\tau, \quad t \in [0, T], \quad (14)$$

where  $\omega(x,t) = u_{txx}(x,t)$ ,

$$a(0) = \frac{\varphi''(x_0) - h_0'(0)}{\varphi(x_0)}, \quad (15)$$

$\varphi^{(IV)}$  is the fourth derivative of the function  $\varphi(x)$ .

**Proof.** By setting  $\vartheta(x,t) = u_t(x,t)$  and differentiating in  $t$ , we reduce (1)-(4) to the problem

$$\vartheta_t - \vartheta_{xx} + a'(t) \int_0^t \vartheta(x,\tau)d\tau + a'(t)\varphi(x) + a(t)\vartheta(x,t) = k(t)\varphi(x) + \int_0^t k(\tau)\vartheta(x,t-\tau)d\tau, \quad (x,t) \in D_T, \quad (16)$$

$$\vartheta|_{t=0} = \varphi''(x) - a(0)\varphi(x), \quad x \in [0, 1], \quad (17)$$

$$\vartheta|_{x=0} = 0, \vartheta|_{x=1} = 0, \quad t \in [0, T], \quad (18)$$

$$\vartheta(x_0,t) = h_0'(t), \quad \int_0^1 \vartheta(x,t) = h_1'(t), \quad t \in [0, T]. \quad (19)$$

From condition (17) and (19), requiring the matching condition at the points  $(0, x_0)$  we obtain

$$a(0) = \frac{\varphi''(x_0) - h_0'(0)}{\varphi(x_0)} = \frac{\varphi'(1) - \varphi'(0) - h_1'(0)}{\int_0^1 \varphi(x)dx}.$$

Hence it follows that if  $(u, k, a)$  is solution of problem (1)-(4), then (16)-(19) has a solution  $(\vartheta, k, a)$  with the same  $k, a$  as well. Let us prove the converse. Let  $(\vartheta, k, a)$  satisfy relations(16)-(19), then

$$u(x,t) = \int_0^t \vartheta(x,\tau)d\tau + \varphi(x).$$

Let us show that relation (1) holds. It follows from (16)-(19) that

$$\begin{aligned} & u_t - u_{xx} + a(t)u - \int_0^t k(t-\tau)u(x,\tau)d\tau = \\ & = \vartheta(x,t) - \int_0^t \vartheta_{xx}(x,\tau)d\tau - \varphi''(x) + a(t) \int_0^t \vartheta(x,\tau)d\tau + a(t)\varphi(x) - \\ & - \int_0^t k(\tau) \int_0^{t-\tau} \vartheta(x,\alpha)d\alpha d\tau - \int_0^t k(\tau)\varphi(x)d\tau = \\ & = \int_0^t \left[ \vartheta_\tau(x,\tau) - \vartheta_{xx}(x,\tau) + a'(\tau) \int_0^\tau \vartheta(x,\alpha)d\alpha + a(\tau)\vartheta(x,\tau) + a'(\tau)\varphi(x) - k(\tau)\varphi(x) - \right. \\ & \left. - \int_0^\tau k(x,\alpha)\vartheta(x,\tau-\alpha)d\alpha \right] d\tau = 0. \end{aligned}$$

This completes the proof of the equivalence of problems (1)-(4) and (16)-(19).

Now consider the second auxiliary problem. It is obtained from problem (16)-(19) for the function  $p(x,t) = \vartheta_x(x,t)$ ,

$$p_t - p_{xx} + a'(t) \int_0^t p(x, \tau) d\tau + a'(t) \varphi'(x) + a(t) p(x, t) = k(t) \varphi'(x) + \int_0^t k(\tau) p(x, t - \tau) d\tau, \quad (20)$$

$$p|_{t=0} = \varphi'''(x) - a(0) \varphi'(x); \quad (21)$$

$$p_x|_{x=0} = 0, \quad p_x|_{x=1} = 0; \quad (22)$$

$$p_x|_{x=x_0} = h_0''(t) + a'(t) h_0(t) + a(t) h_0'(t) - k(t) \varphi(x_0) - \int_0^t k(\tau) h_0'(t - \tau) d\tau, \quad (23)$$

$$\int_0^1 p_x(x, t) dx = h_1''(t) + a'(t) h_1(t) + a(t) h_1'(t) - k(t) h_1(0) - \int_0^t k(\tau) h_1'(t - \tau) d\tau. \quad (24)$$

The derivation of the equations in the opposite way under the matching conditions

$$\begin{aligned} \varphi^{(IV)}(0) - a(0) \varphi''(0) &= \varphi^{(IV)}(1) - a(0) \varphi''(1) = 0, \\ h_0''(0) + a'(0) h_0(0) + a(0) h_0'(0) - k(0) \varphi(x_0) &= \varphi^{(IV)}(x_0) - a(0) \varphi''(x_0), \\ \varphi^{(III)}(1) - \varphi^{(III)}(0) + a(0) (\varphi'(0) - \varphi'(1)) &= h_1''(0) + a'(0) h_1(0) + a(0) h_1'(0) - k(0) h_1(0), \end{aligned}$$

which follows (21)-(23), can be proved by complete analogy with the previous case.

Therefore, if the problem (16)-(19) has a solution  $(\vartheta, k, a)$ , then the problem (20)-(23) has a solution  $(p, k, a)$  with the same  $k, a$ , moreover,  $p(x, t) = \vartheta_x(x, t)$ . Conversely, let  $(p, k, a)$  satisfy relations (20)-(23).

Hence it follows that

$$\vartheta(x, 0) = \int_0^x p(y, 0) dy = \int_0^x (\varphi'''(y) - a(0) \varphi'(y)) dy = \varphi''(x) - a(0) \varphi(x);$$

i.e., condition (17) is satisfied. It remains to show that equation (16) holds. It follows from relations (20)-(23) that

$$\begin{aligned} \vartheta_t - \vartheta_{xx} + a'(t) \int_0^t \vartheta(x, \tau) d\tau + a'(t) \varphi(x) + a(t) \vartheta(x, t) - k(t) \varphi(x) - \int_0^t k(\tau) \vartheta(x, t - \tau) d\tau &= \\ = \int_0^x [p_t(y, t) - p_{yy}(y, t) + a'(t) \int_0^t p(y, \tau) d\tau + a'(t) \varphi'(y) + a(t) p(y, t) - & \\ - k(t) \varphi'(y) - \int_0^t k(\tau) p(y, t - \tau) d\tau] dy + a'(t) \varphi(0) - k(t) \varphi(0) &= 0. \end{aligned}$$

We have thereby proved the equivalence of problems (16)-(19) and (20)-(23). In similar way, one can show that problem (20)-(23) is equivalent to problem (10)-(13) for the function  $\omega = p_x$ . This implies the equivalence of problems (1)-(4) and (10)-(13). The lemma is proved.

## FORMULATION OF MAIN RESULT AND ITS PROOF

In this section existence and uniqueness for the problem (10)-(13) is proved using the contraction mapping principle. The idea is to write the integral equations for unknown functions  $\omega(x, t), k(t), a(t)$  as a system with a nonlinear operator, and prove that this operator is a contraction mapping operator for sufficiently small  $T$ . The existence and uniqueness then follow immediately.

From problem (10)-(13), we obtain

$$\begin{aligned} \omega(x, t) &= \omega_0(x, t) + \int_0^t \int_0^1 G(x, \xi, t - \tau) k(\tau) \varphi(\xi) d\xi d\tau - \int_0^t \int_0^1 G(x, \xi, t - \tau) a(\tau) \omega(\xi, \tau) d\xi d\tau - \\ &- \int_0^t \int_0^1 G(x, \xi, t - \tau) a'(\tau) \varphi(\xi) d\xi d\tau - \int_0^t \int_0^1 G(x, \xi, t - \tau) a'(\tau) \int_0^\tau \omega(\xi, \alpha) d\alpha d\xi d\tau + \\ &+ \int_0^t \int_0^1 G(x, \xi, t - \tau) \int_0^\tau k(\alpha) \omega(\xi, \tau - \alpha) d\alpha d\xi d\tau, \end{aligned} \quad (25)$$

where

$$\omega_0(x, t) = \int_0^1 G(x, \xi, t) (\varphi^{(IV)}(\xi) - a(0)\varphi'(\xi)) d\xi.$$

By setting  $x = x_0$  in integral equation (25) and and integrated over  $x$  from 0 to 1 in equation (25) by taking into account condition (13), for the functions  $k(t), a'(t)$ , we obtain the integral equations

$$\begin{aligned} k(t) &= \frac{1}{\Delta} \left[ h_1(t) (\omega_0(x_0, t) - h_0''(t)) - h_0(t) \left( \int_0^1 \omega_0(x, t) dx - h_1''(t) \right) \right] + \\ &+ \frac{1}{\Delta} \int_0^t \int_0^1 h_1(t) G(x_0, \xi, t - \tau) \left[ k(\tau) \varphi(\xi) - a(\tau) \omega(\xi, \tau) - a'(\tau) \varphi(\xi) - a'(\tau) \int_0^\tau \omega(\xi, \tau - \alpha) d\alpha \right] d\xi d\tau - \\ &- \frac{1}{\Delta} \int_0^1 \int_0^t \int_0^1 h_0(t) G(x, \xi, t - \tau) \left[ k(\tau) \varphi(\xi) - a(\tau) \omega(\xi, \tau) - a'(\tau) \varphi(\xi) - a'(\tau) \int_0^\tau \omega(\xi, \tau - \alpha) d\alpha \right] d\xi d\tau dx - \\ &- \frac{a(t)}{\Delta} \left( h_1(t) h_0'(t) - h_0(t) h_1'(t) \right) + \frac{1}{\Delta} \int_0^t k(\tau) \left( h_1(t) h_0'(t - \tau) - h_0(t) h_1'(t - \tau) \right) d\tau, \end{aligned} \quad (26)$$

where

$$\Delta = h_1(0)h_0(t) - \varphi(x_0)h_1(t).$$

$$\begin{aligned} a'(t) &= \frac{1}{\Delta} \left[ h_1(0) (\omega_0(x_0, t) - h_0''(t)) - \varphi(x_0) \left( \int_0^1 \omega_0(x, t) dx - h_1''(t) \right) \right] + \\ &+ \frac{1}{\Delta} \int_0^t \int_0^1 h_2(0) G(x_0, \xi, t - \tau) \left[ k(\tau) \varphi(\xi) - a(\tau) \omega(\xi, \tau) - a'(\tau) \varphi(\xi) - a'(\tau) \int_0^\tau \omega(\xi, \tau - \alpha) d\alpha \right] d\xi d\tau - \\ &- \frac{1}{\Delta} \int_0^1 \int_0^t \int_0^1 \varphi(x_0) G(x, \xi, t - \tau) \left[ k(\tau) \varphi(\xi) - a(\tau) \omega(\xi, \tau) - a'(\tau) \varphi(\xi) - a'(\tau) \int_0^\tau \omega(\xi, \tau - \alpha) d\alpha \right] d\xi d\tau dx - \\ &- \frac{a(t)}{\Delta} \left( h_1(0) h_0'(t) - \varphi(x_0) h_1'(t) \right) + \frac{1}{\Delta} \int_0^t k(\tau) \left( h_1(0) h_0'(t - \tau) - \varphi(x_0) h_1'(t - \tau) \right) d\tau. \end{aligned} \quad (27)$$

$$a(t) = a(0) + \int_0^t a'(\tau) d\tau. \quad (28)$$

Equations (25)-(28) form a complete system of integral equations for the unknown functions  $\omega(x, t), k(t), a'(t), a(t)$ . We represent this system in the form of the operator equation

$$\psi = A\psi, \quad (29)$$

where  $\psi = (\psi_1, \psi_2, \psi_3, \psi_4) := (\omega(x, t), k(t) + a(t)\beta(t), a'(t) + a(t)\gamma(t), a(t))$ ,  $\left( \beta(t) = \frac{1}{\Delta} (h_1(t)h_0'(t) - h_0(t)h_1'(t)), \gamma(t) = \frac{1}{\Delta} (h_1(0)h_0'(t) - \varphi(x_0)h_1'(t)) \right)$  is the vector-function and unknown functions are represented by functions  $\psi_1, \psi_2, \psi_3, \psi_4$  as follows:

$$\omega(x, t) = \psi_1(x, t), \quad k(t) = \psi_2(t) - \psi_4(t)\beta(t), \quad a'(t) = \psi_3(t) - \psi_4(t)\gamma(t), \quad a(t) = \psi_4(t).$$

$A = (A_1, A_2, A_3, A_4)$  is defined by the right sides of equations (25)-(28):

$$\begin{aligned} (A\psi)_1(x, t) &= \omega_0(x, t) + \int_0^t \int_0^1 G(x, \xi, t - \tau) (\psi_2(\tau) - \psi_4(\tau)\beta(\tau)) \varphi(\xi) d\xi d\tau - \\ &- \int_0^t \int_0^1 G(x, \xi, t - \tau) \psi_4(\tau) \psi_1(\xi, \tau) d\xi d\tau - \int_0^t \int_0^1 G(x, \xi, t - \tau) (\psi_3(\tau) - \psi_4(\tau)\gamma(\tau)) \varphi(\xi) d\xi d\tau - \\ &- \int_0^t \int_0^1 G(x, \xi, t - \tau) (\psi_3(\tau) - \psi_4(\tau)\gamma(\tau)) \int_0^\tau \psi_1(\xi, \alpha) d\alpha d\xi d\tau + \\ &+ \int_0^t \int_0^1 G(x, \xi, t - \tau) \int_0^\tau (\psi_2(\alpha) - \psi_4(\alpha)\beta(\alpha)) \psi_1(\xi, \tau - \alpha) d\alpha d\xi d\tau, \end{aligned}$$

$$\begin{aligned}
(A\psi)_2(t) &= \frac{1}{\Delta} \left[ h_1(t) (\omega_0(x_0, t) - h_0''(t)) - h_0(t) \left( \int_0^1 \omega_0(x, t) dx - h_1''(t) \right) \right] + \\
&+ \frac{1}{\Delta} \int_0^t \int_0^1 h_1(t) G(x_0, \xi, t - \tau) \left[ (\psi_2(\tau) - \psi_4(\tau)\beta(\tau)) \varphi(\xi) - \psi_4(\tau)\psi_1(\xi, \tau) - \right. \\
&- (\psi_3(\tau) - \psi_4(\tau)\gamma(\tau)) \varphi(\xi) - (\psi_3(\tau) - \psi_4(\tau)\gamma(\tau)) \int_0^\tau \psi_1(\xi, \tau - \alpha) d\alpha \left. \right] d\xi d\tau - \\
&- \frac{1}{\Delta} \int_0^1 \int_0^t \int_0^1 h_0(t) G(x, \xi, t - \tau) \left[ (\psi_2(\tau) - \psi_4(\tau)\beta(\tau)) \varphi(\xi) - \psi_4(\tau)\psi_1(\xi, \tau) - \right. \\
&- (\psi_3(\tau) - \psi_4(\tau)\gamma(\tau)) \varphi(\xi) - (\psi_3(\tau) - \psi_4(\tau)\gamma(\tau)) \int_0^\tau \psi_1(\xi, \tau - \alpha) d\alpha \left. \right] d\xi d\tau dx + \\
&+ \frac{1}{\Delta} \int_0^t (\psi_2(\tau) - \psi_4(\tau)\beta(\tau)) (h_1(t)h_0'(t - \tau) - h_0(t)h_1'(t - \tau)) d\tau,
\end{aligned}$$

$$\begin{aligned}
(A\psi)_3(t) &= \frac{1}{\Delta} \left[ h_1(0) (\omega_0(x_0, t) - h_0''(t)) - \varphi(x_0) \left( \int_0^1 \omega_0(x, t) dx - h_1''(t) \right) \right] + \\
&+ \frac{1}{\Delta} \int_0^t \int_0^1 h_2(0) G(x_0, \xi, t - \tau) \left[ (\psi_2(\tau) - \psi_4(\tau)\beta(\tau)) \varphi(\xi) - \psi_4(\tau)\psi_1(\xi, \tau) - \right. \\
&- (\psi_3(\tau) - \psi_4(\tau)\gamma(\tau)) \varphi(\xi) - (\psi_3(\tau) - \psi_4(\tau)\gamma(\tau)) \int_0^\tau \psi_1(\xi, \tau - \alpha) d\alpha \left. \right] d\xi d\tau - \\
&- \frac{1}{\Delta} \int_0^1 \int_0^t \int_0^1 \varphi(x_0) G(x, \xi, t - \tau) \left[ (\psi_2(\tau) - \psi_4(\tau)\beta(\tau)) \varphi(\xi) - \psi_4(\tau)\psi_1(\xi, \tau) - \right. \\
&- (\psi_3(\tau) - \psi_4(\tau)\gamma(\tau)) \varphi(\xi) - (\psi_3(\tau) - \psi_4(\tau)\gamma(\tau)) \int_0^\tau \psi_1(\xi, \tau - \alpha) d\alpha \left. \right] d\xi d\tau dx - \\
&+ \frac{1}{\Delta} \int_0^t (\psi_2(\tau) - \psi_4(\tau)\beta(\tau)) (h_1(0)h_0'(t - \tau) - \varphi(x_0)h_1'(t - \tau)) d\tau,
\end{aligned}$$

$$(A\psi)_4(t) = a(0) + \int_0^t (\psi_3(\tau) - \psi_4(\tau)\gamma(\tau)) d\tau.$$

Let  $\psi_0 := (\psi_{01}, \psi_{02}, \psi_{03}, \psi_{04})$ , where

$$\psi_{01} = \omega_0(x, t), \psi_{02} = \frac{1}{\Delta} \left[ h_1(t) (\omega_0(x_0, t) - h_0''(t)) - h_0(t) \left( \int_0^1 \omega_0(x, t) dx - h_1''(t) \right) \right],$$

$$\psi_{03} = \frac{1}{\Delta} \left[ h_1(0) (\omega_0(x_0, t) - h_0''(t)) - \varphi(x_0) \left( \int_0^1 \omega_0(x, t) dx - h_1''(t) \right) \right], \psi_{04} = a(0).$$

**Theorem 1.** *If the conditions  $\varphi(x) \in C^4(0, 1)$ ,  $h_i(t) \in C^2[0, T]$ ,  $i = 0, 1$ ,  $\varphi(0) = \varphi(1) = 0$ ,  $\varphi(x_0) = h_0(0)$ ,  $\int_0^1 \varphi(x) dx = h_1(0)$  are met, then there exists sufficiently small number  $T^* \in (0, T)$  that the solution to the system of integral equations (25)–(28) in the class of functions  $\omega(x, t) \in C^{2,1}(D_T)$ ,  $k(t) \in C(0, T]$ ,  $a(t) \in C^1(0, T]$  exists is unique. Thus, there is the unique classical solution to the problem (1)–(4).*

**Proof.** Consider the functional space of vector functions  $\psi \in C(D_T)$  with the norm given by the relation

$$\begin{aligned}
\|\psi\| &= \max \left\{ \max_{(x,t) \in \bar{D}_T} |\psi_1(x, t)|, \max_{t \in [0, T]} |\psi_2(t)|, \max_{t \in [0, T]} |\psi_3(t)|, \max_{t \in [0, T]} |\psi_4(t)| \right\} = \\
&= \max \left\{ \|\psi_1\|, \|\psi_2\|, \|\psi_3\|, \|\psi_4\| \right\}.
\end{aligned}$$

In this space, by  $B(\psi_0, \|\psi_0\|)$  we denote the ball with center  $\psi_0$  and radius  $\|\psi_0\|$ , i.e.  $B(\psi_0, \|\psi_0\|) = \{\psi : \|\psi - \psi_0\| \leq \|\psi_0\|\}$ . Obviously,  $\|\psi\| \leq 2\|\psi_0\|$ .



Let us show that  $A$  is a contraction operator in the ball  $B(\psi_0, \|\psi_0\|)$  provided that  $T$  is sufficiently small number. For simplicity, we denote

$$h_0 := \max \left\{ \sup_{t \in (0, T)} |h_i(t)|, \sup_{t \in (0, T)} |h'_i(t)|, \sup_{t \in (0, T)} |h''_i(t)| \right\}, i = 0, 1, \quad \beta = \max_{t \in [0, T]} |\beta(t)|, \gamma = \max_{t \in [0, T]} |\gamma(t)|$$

$$\varphi_0 := \max \left\{ \sup_{x \in (0, 1)} |\varphi(x)|, \sup_{x \in (0, 1)} |\varphi'(x)|, \sup_{x \in (0, 1)} |\varphi''(x)| \right\}.$$

Let us verify the first condition of a fixed point argument [43]. Let  $\psi \in B$ ; then  $\|\psi\| \leq 2\|\psi_0\|$ . In addition, for  $(x, t) \in D_T$ , we have estimates

$$\begin{aligned} \|(A\psi)_1 - \psi_{01}\| &= \sup_{(x, t) \in D_T} |(A\psi)_1 - \psi_{01}| \leq \\ &\leq \sup_{(x, t) \in D_T} \left| \int_0^t \int_0^1 G(x, \xi, t - \tau) (\psi_2(\tau) - \psi_4(\tau)\beta(\tau)) \varphi(\xi) d\xi d\tau \right| + \\ &+ \sup_{(x, t) \in D_T} \left| \int_0^t \int_0^1 G(x, \xi, t - \tau) \psi_4(\tau) \psi_1(\xi, \tau) d\xi d\tau \right| + \\ &+ \sup_{(x, t) \in D_T} \left| \int_0^t \int_0^1 G(x, \xi, t - \tau) (\psi_3(\tau) - \psi_4(\tau)\gamma(\tau)) \varphi(\xi) d\xi d\tau \right| + \\ &\sup_{(x, t) \in D_T} \left| \int_0^t \int_0^1 G(x, \xi, t - \tau) (\psi_3(\tau) - \psi_4(\tau)\gamma(\tau)) \int_0^\tau \psi_1(\xi, \alpha) d\alpha d\xi d\tau \right| + \\ &+ \sup_{(x, t) \in D_T} \left| \int_0^t \int_0^1 G(x, \xi, t - \tau) \int_0^\tau (\psi_2(\alpha) - \psi_4(\alpha)\beta(\alpha)) \psi_1(\xi, \tau - \alpha) d\alpha d\xi d\tau \right| \leq \\ &\leq 2T\|\psi_0\| [(2 + \beta + \gamma)\varphi_0 + \|\psi_0\|(1 + 2T + T\beta + T\gamma)]. \end{aligned}$$

$$\begin{aligned} \|(A\psi)_2 - \psi_{02}\| &= \sup_{t \in (0, T)} |((A\psi)_2 - \psi_{02})| \leq \\ &\leq \frac{4Th_0\|\psi_0\|}{\Delta} (\varphi_0(2 + \beta + \gamma) + \|\psi_0\|(1 + 2T + T\gamma + T\beta) + h_0(1 + \beta)); \end{aligned}$$

$$\begin{aligned} \|(A\psi)_3 - \psi_{03}\| &= \sup_{t \in (0, T)} |((A\psi)_3 - \psi_{03})| \leq \\ &\leq \frac{4T\varphi_0\|\psi_0\|}{\Delta} (\varphi_0(2 + \beta + \gamma) + \|\psi_0\|(1 + 2T + T\gamma + T\beta) + h_0(1 + \beta)); \end{aligned}$$

$$\|(A\psi)_4 - \psi_{04}\| = \sup_{t \in (0, T)} |((A\psi)_4 - \psi_{04})| \leq 2\|\psi_0\|T(1 + \gamma).$$

Denote  $T_1 = \min\{T_{11}, T_{12}, T_{13}, T_{14}\}$ , where  $T_{1i}, i = \overline{1, 4}$  are the positive roots of the following equations, respectively

$$\begin{aligned} 2T \left[ (2 + \beta + \gamma)\varphi_0 + \|\psi_0\|(1 + 2T + T\beta + T\gamma) \right] &= 1, \\ \frac{4Th_0}{\Delta} \left( \varphi_0(2 + \beta + \gamma) + \|\psi_0\|(1 + 2T + T\gamma + T\beta) + h_0(1 + \beta) \right) &= 1, \\ \frac{4T\varphi_0}{\Delta} \left( \varphi_0(2 + \beta + \gamma) + \|\psi_0\|(1 + 2T + T\gamma + T\beta) + h_0(1 + \beta) \right) &= 1, \\ 2T(1 + \gamma) &= 1. \end{aligned}$$

If we choose  $T$  so that  $T < T_1$ , then  $A\psi \in B(\psi_0, \|\psi_0\|)$ .

We now check the second condition of a fixed point argument

$$\begin{aligned}
\|(A\psi^1 - A\psi^2)_1\| &\leq \sup_{(x,t) \in D_T} \left| \int_0^t \int_0^1 G(x, \xi, t - \tau) \left( [\psi_2^1(\tau) - \psi_2^2(\tau)] - [\psi_4^1(\tau) - \psi_4^2(\tau)]\beta(\tau) \right) \varphi(\xi) d\xi d\tau \right| + \\
&+ \sup_{(x,t) \in D_T} \left| \int_0^t \int_0^1 G(x, \xi, t - \tau) [\psi_4^1(\tau)\psi_1^1(\xi, \tau) - \psi_4^2(\tau)\psi_1^2(\xi, \tau)] d\xi d\tau \right| + \\
&+ \sup_{(x,t) \in D_T} \left| \int_0^t \int_0^1 G(x, \xi, t - \tau) \left( [\psi_3^1(\tau) - \psi_3^2(\tau)] - [\psi_4^1(\tau) - \psi_4^2(\tau)]\gamma(\tau) \right) \varphi(\xi) d\xi d\tau \right| + \\
&+ \sup_{(x,t) \in D_T} \left| \int_0^t \int_0^1 G(x, \xi, t - \tau) \int_0^\tau [\psi_1^1(\xi, \alpha)\psi_3^1(\tau) - \psi_1^2(\xi, \alpha)\psi_3^2(\tau)] d\alpha d\xi d\tau \right| + \\
&+ \sup_{(x,t) \in D_T} \left| \int_0^t \int_0^1 G(x, \xi, t - \tau) \int_0^\tau [\psi_1^1(\xi, \alpha)\psi_4^1(\tau) - \psi_1^2(\xi, \alpha)\psi_4^2(\tau)]\gamma(\tau) d\alpha d\xi d\tau \right| + \\
&+ \sup_{(x,t) \in D_T} \left| \int_0^t \int_0^1 G(x, \xi, t - \tau) \int_0^\tau [\psi_1^1(\xi, \tau - \alpha)\psi_2^1(\alpha) - \psi_1^2(\xi, \tau - \alpha)\psi_2^2(\alpha)] d\alpha d\xi d\tau \right| + \\
&+ \sup_{(x,t) \in D_T} \left| \int_0^t \int_0^1 G(x, \xi, t - \tau) \int_0^\tau [\psi_1^1(\xi, \tau - \alpha)\psi_4^1(\alpha) - \psi_1^2(\xi, \tau - \alpha)\psi_4^2(\alpha)]\beta(\alpha) d\alpha d\xi d\tau \right|.
\end{aligned}$$

The integrand in the second integral can be estimated as follows:

$$\begin{aligned}
\|\psi_4^1\psi_1^1 - \psi_4^2\psi_1^2\| &= \|(\psi_4^1 - \psi_4^2)\psi_1^1 + \psi_4^2(\psi_1^1 - \psi_1^2)\| \leq \\
&\leq 2\|\psi^1 - \psi^2\| \max(\|\psi_1^1\|, \|\psi_4^2\|) \leq 4\|\psi_0\| \|\psi^1 - \psi^2\|.
\end{aligned}$$

Therefore,

$$\|(A\psi^1 - A\psi^2)_1\| \leq \|\psi^1 - \psi^2\| (2\|\psi_0\|(2 + \beta + \gamma)T^2 + ((2 + \beta + \gamma)\varphi_0 + 4\|\psi_0\|)T);$$

The next components can be estimated in a similar way,

$$\begin{aligned}
\|(A\psi^1 - A\psi^2)_2\| &\leq \frac{2h_0}{\Delta} (((2 + \beta + \gamma)\varphi_0 + h_0(1 + \beta) + 4\|\psi_0\|)T + 2\|\psi_0\|(2 + \beta + \gamma)T^2) \|\psi^1 - \psi^2\|; \\
\|(A\psi^1 - A\psi^2)_3\| &\leq \frac{2\varphi_0}{\Delta} (((2 + \beta + \gamma)\varphi_0 + h_0(1 + \beta) + 4\|\psi_0\|)T + 2\|\psi_0\|(2 + \beta + \gamma)T^2) \|\psi^1 - \psi^2\|; \\
\|(A\psi^1 - A\psi^2)_4\| &\leq (1 + \gamma)T \|\psi^1 - \psi^2\|.
\end{aligned}$$

Denote  $T_2 = (T_{21}, T_{22}, T_{23}, T_{24})$ ; where  $T_{2i}, i = \overline{1, 4}$  are the positive roots of the following equations, respectively

$$\begin{aligned}
2\|\psi_0\| \left( (2 + \beta + \gamma)T^2 + ((2 + \beta + \gamma)\varphi_0 + 4\|\psi_0\|)T \right) &= 1, \\
\frac{2h_0}{\Delta} \left( ((2 + \beta + \gamma)\varphi_0 + h_0(1 + \beta) + 4\|\psi_0\|)T + 2\|\psi_0\|(2 + \beta + \gamma)T^2 \right) &= 1, \\
\frac{2\varphi_0}{\Delta} \left( ((2 + \beta + \gamma)\varphi_0 + h_0(1 + \beta) + 4\|\psi_0\|)T + 2\|\psi_0\|(2 + \beta + \gamma)T^2 \right) &= 1, \\
(1 + \gamma)T &= 1.
\end{aligned}$$

Therefore, if the number  $T^*$  is small enough to ensure that condition  $T^* \in (0, \min(T_1, T_2))$  is satisfied, then  $A$  is contraction operator on  $B$ . Then, by the Banach principle, integral equations (25)-(28) has a unique solution in  $B$ . Theorem is proved.

If we put the coefficient  $a(t)$  and the kernel  $k(t)$  to the problem (1), get the direct problem (1) - (3). In this case, the function  $u(x, t)$  is defined as uniquely.

## CONCLUSION

In this work, inverse problem was considered for determining the coefficient  $a(t)$  and the kernel  $k(t)$  included in the equation (1) with by using overdetermination conditions (4) of the solution of problem with the initial and boundary

conditions (2), (3). Sufficiently conditions are obtained for given functions, under which the inverse problem have unique solutions for small interval.

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